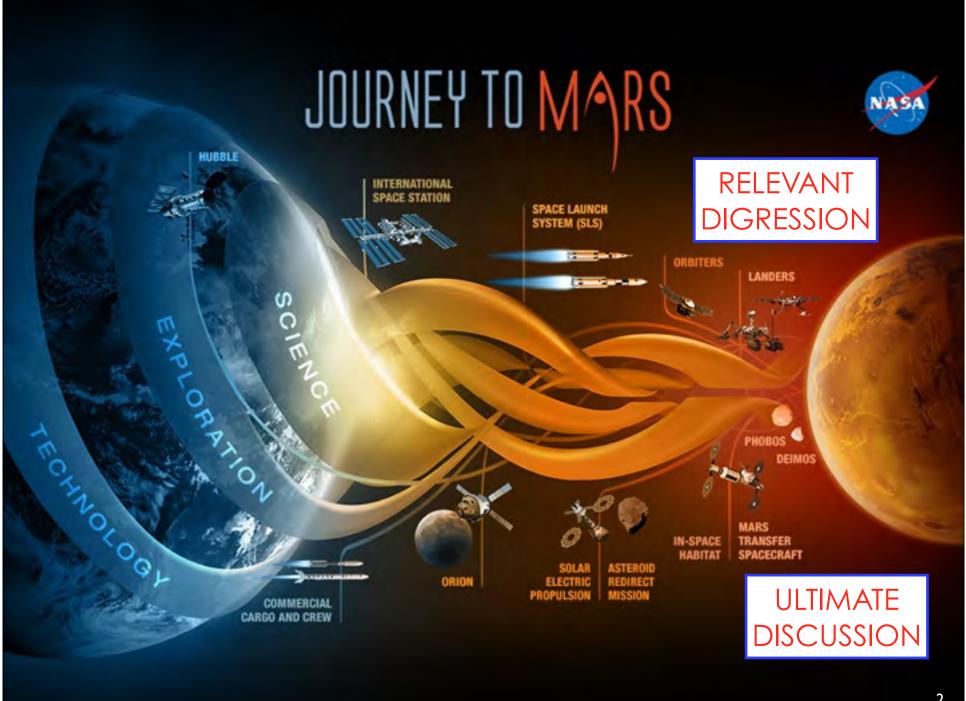


Lessons from Robotic Exploration for Human Missions to Mars

Prof. Jim Bell ASU/School of Earth & Space Exploration President, The Planetary Society

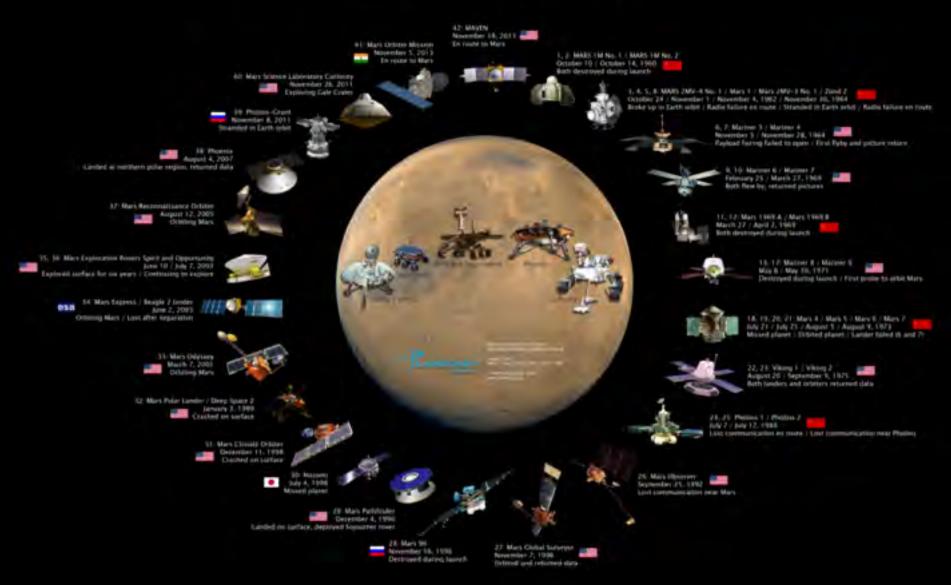
Future In Space Operations (FISO) Working Group Presentation 31 August 2016





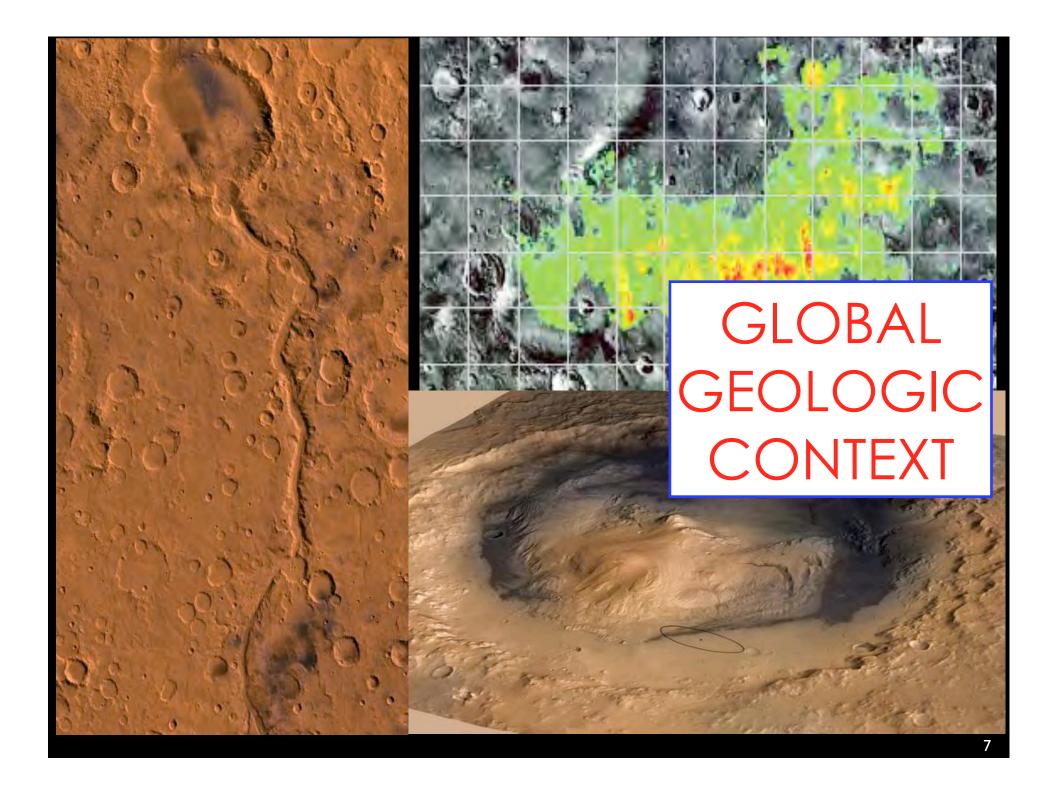
- 1. Robotic exploration IS human exploration
- 2. Robotic exploration ENABLES science AND human exploration
- 3. LATENCY is complex, and its role in future exploration needs careful study

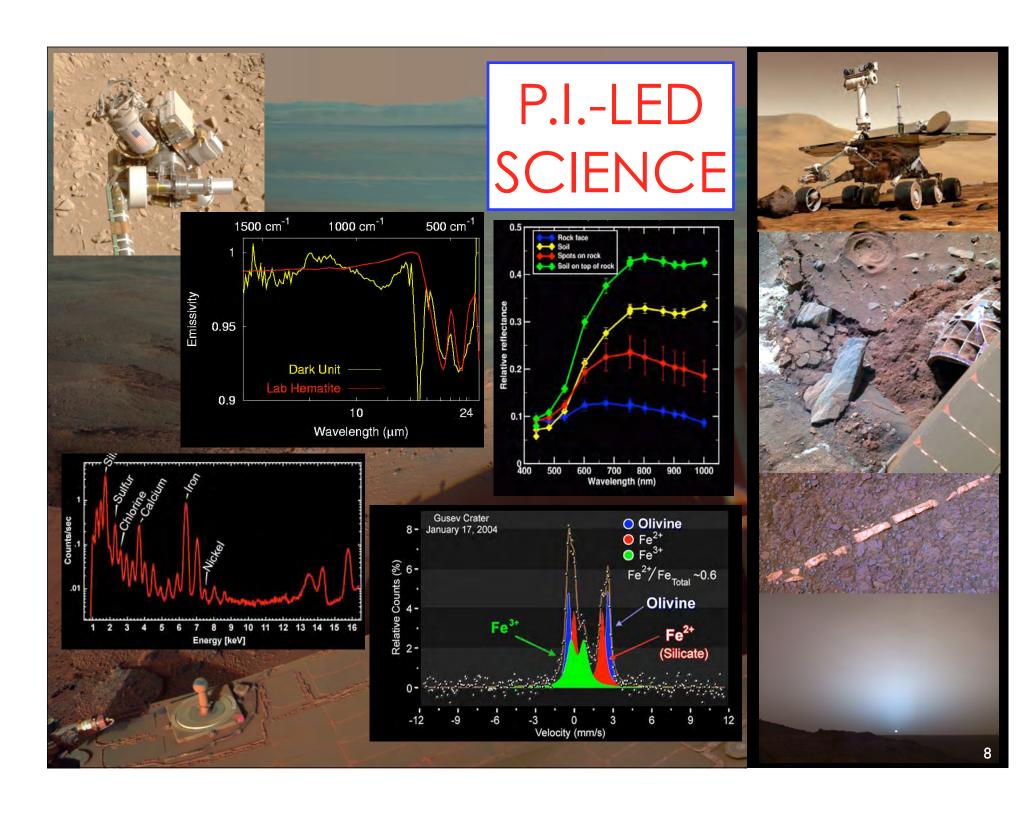
### Mars Exploration Family Portrait







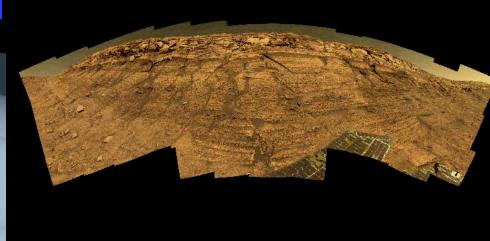


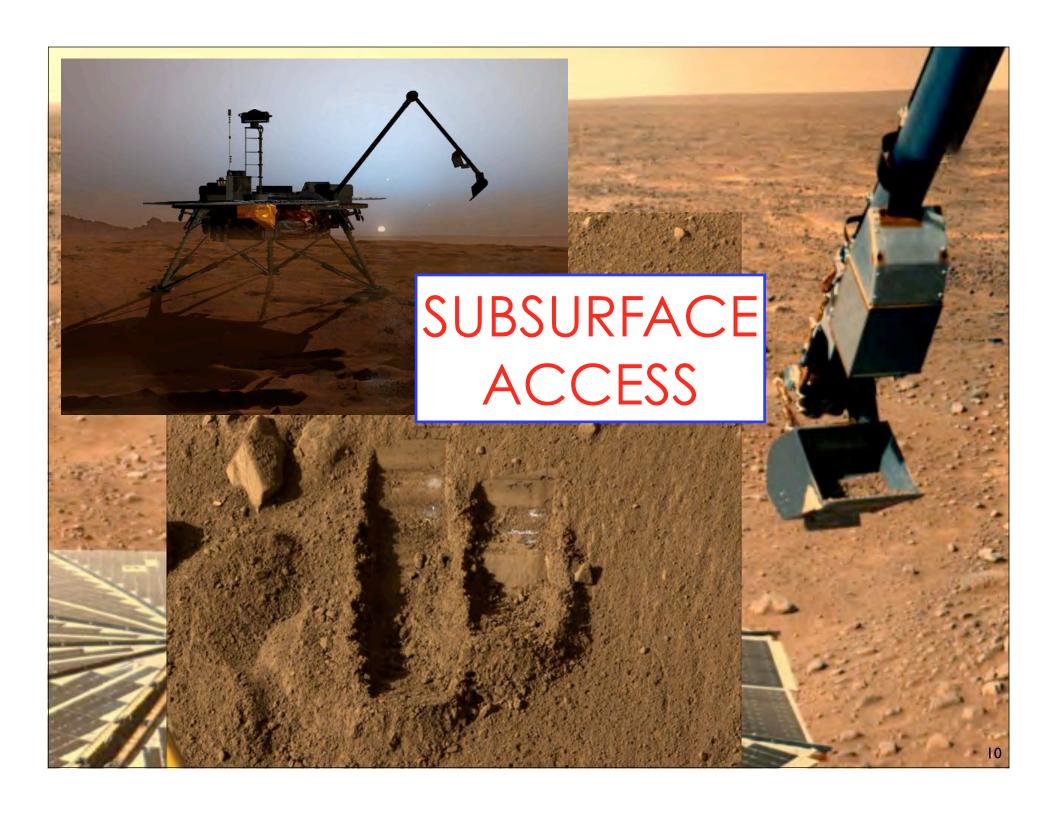


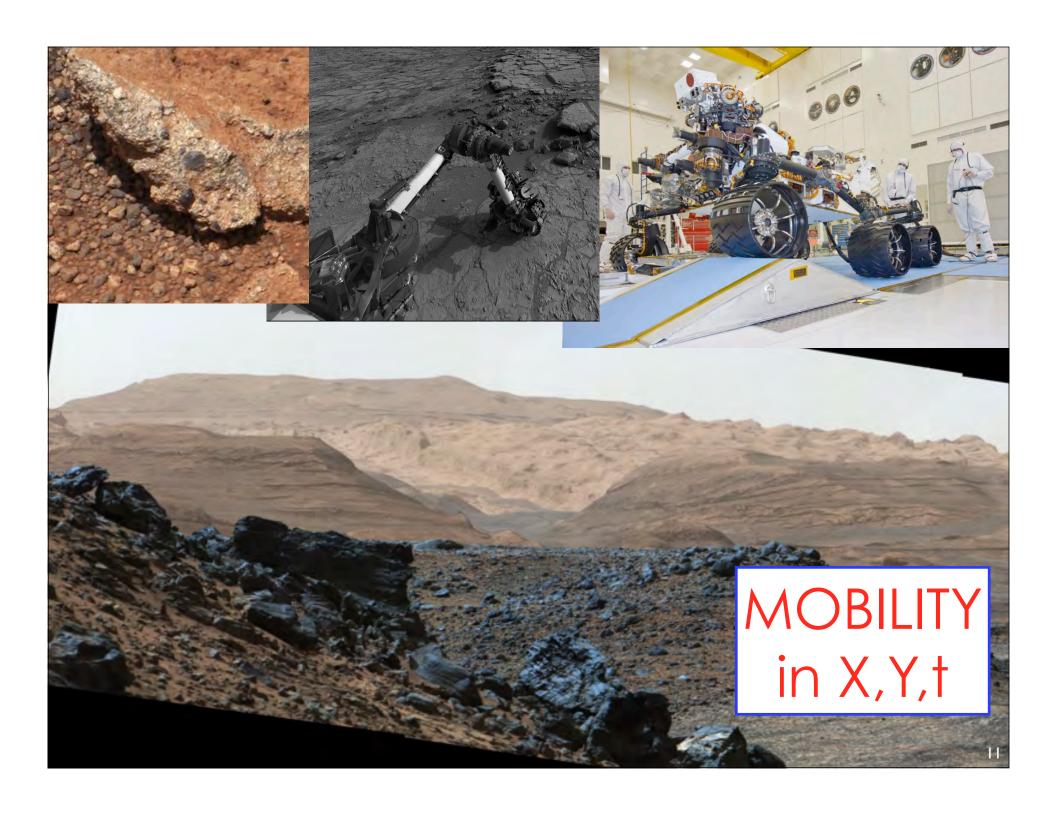
















1. Robotic exploration IS human exploration

MOBILITY in X,Y,Z,t

SUBSURFACE ACCESS **ASTROBIOLOGY** 

P.I.-LED SCIENCE GLOBAL
GEOLOGIC
CONTEXT

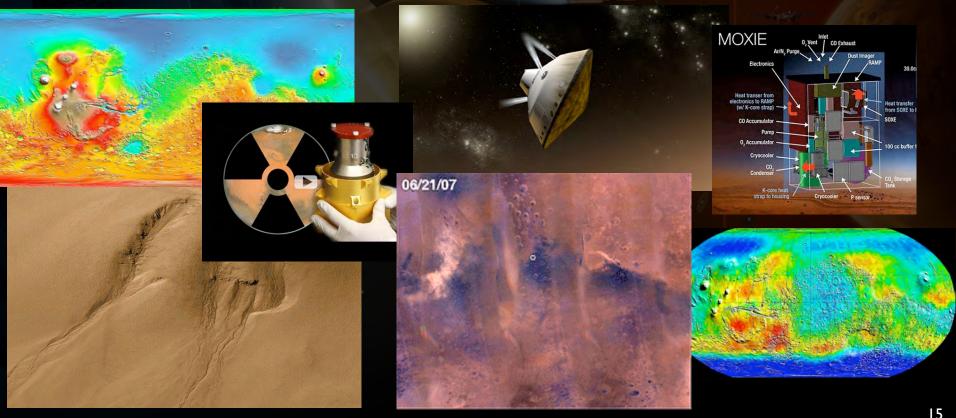


2. Robotic exploration ENABLES SCIENCE and human exploration





2. Robotic exploration ENABLES science AND HUMAN EXPLORATION



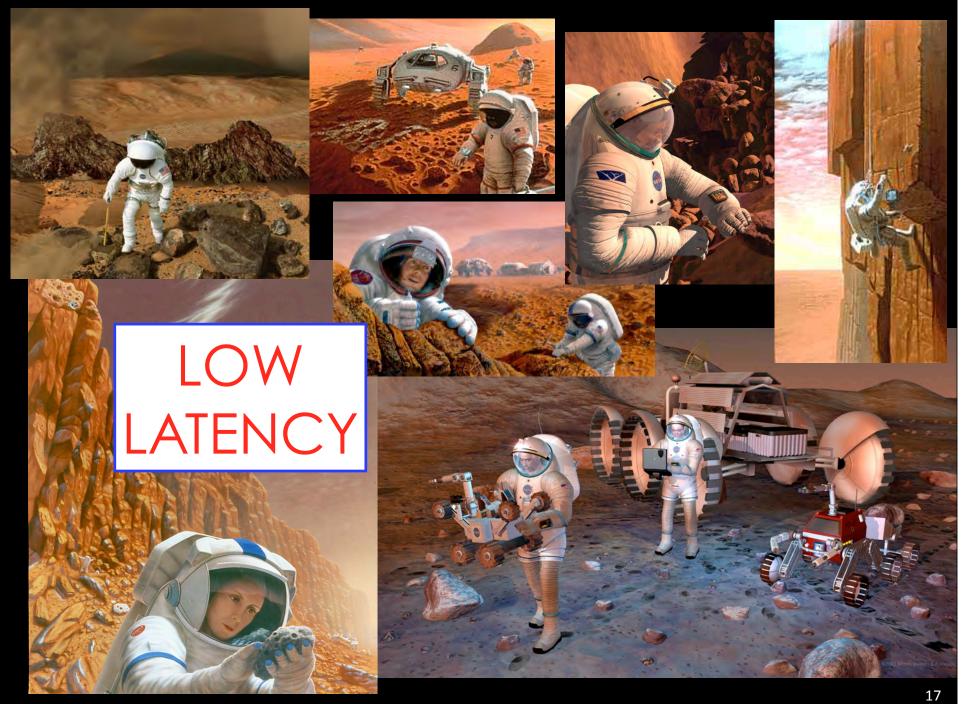


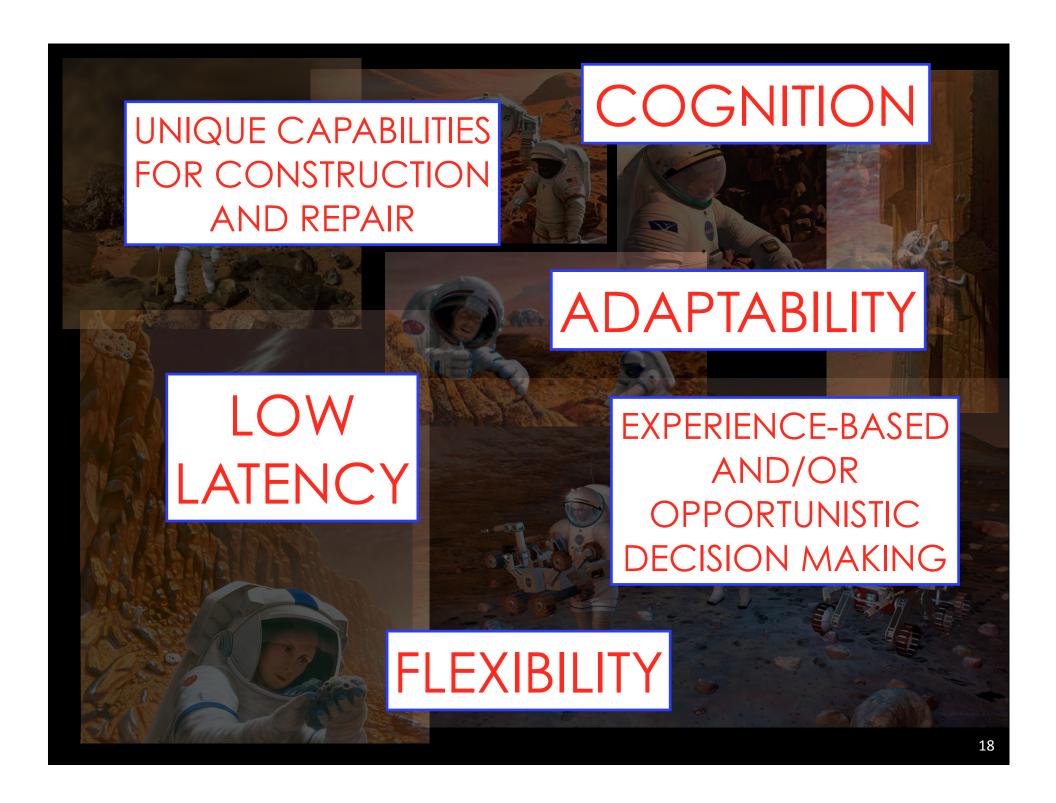
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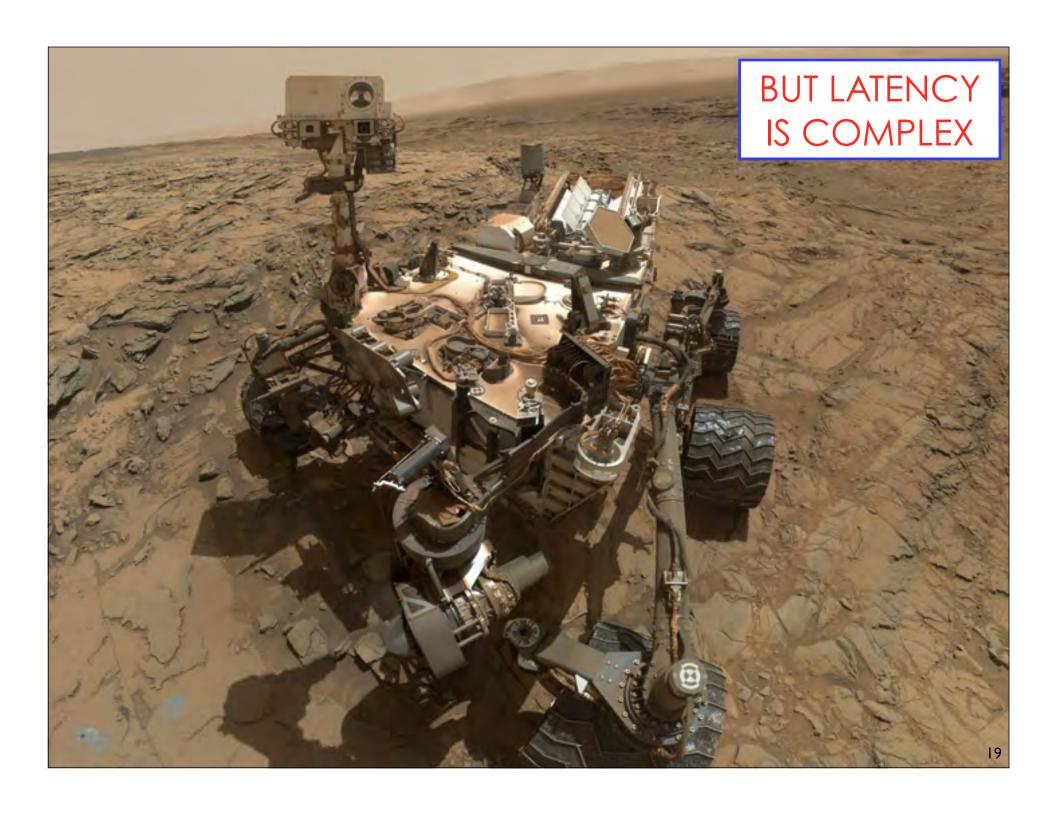


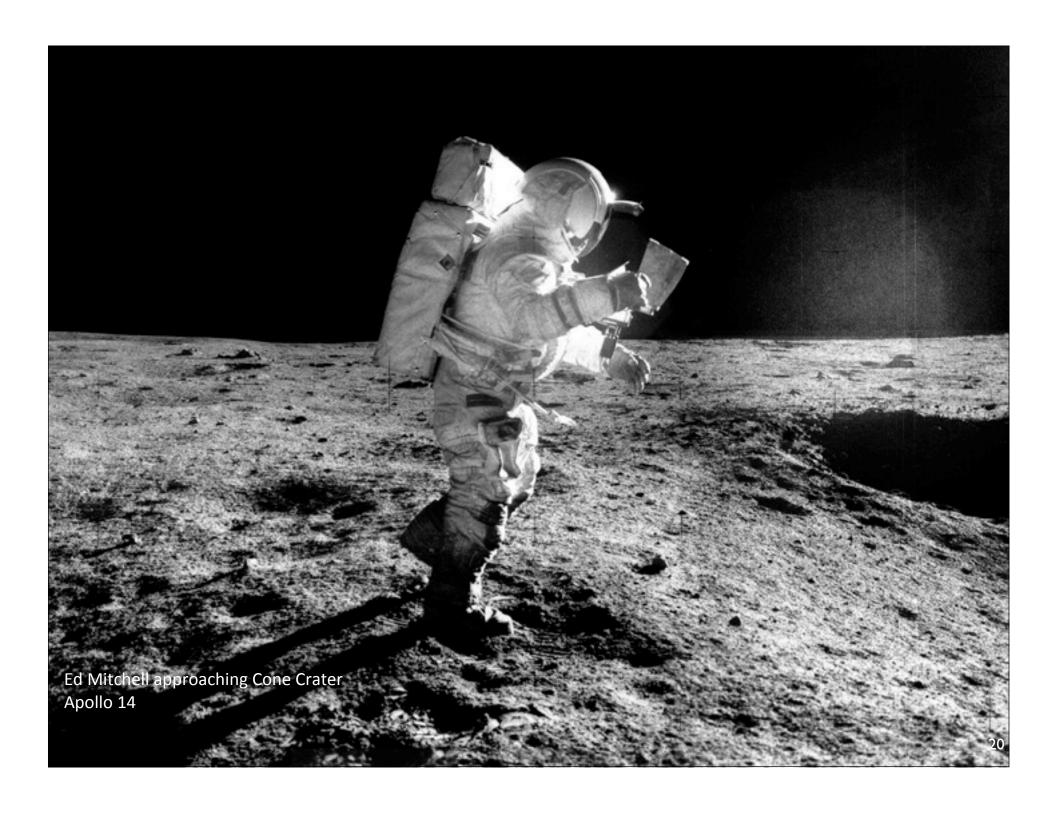
"...the unfortunate truth is that most things our rovers can do in a perfect sol a human explorer could do in less than a minute."

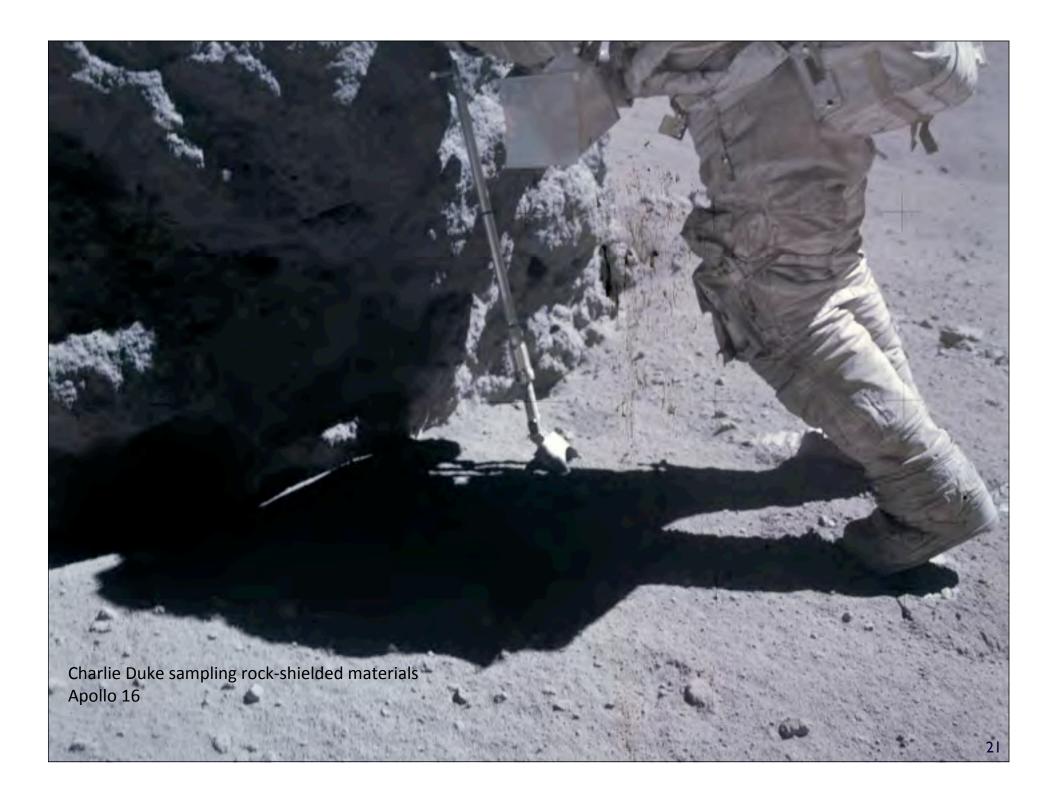
- Steve Squyres, Roving Mars

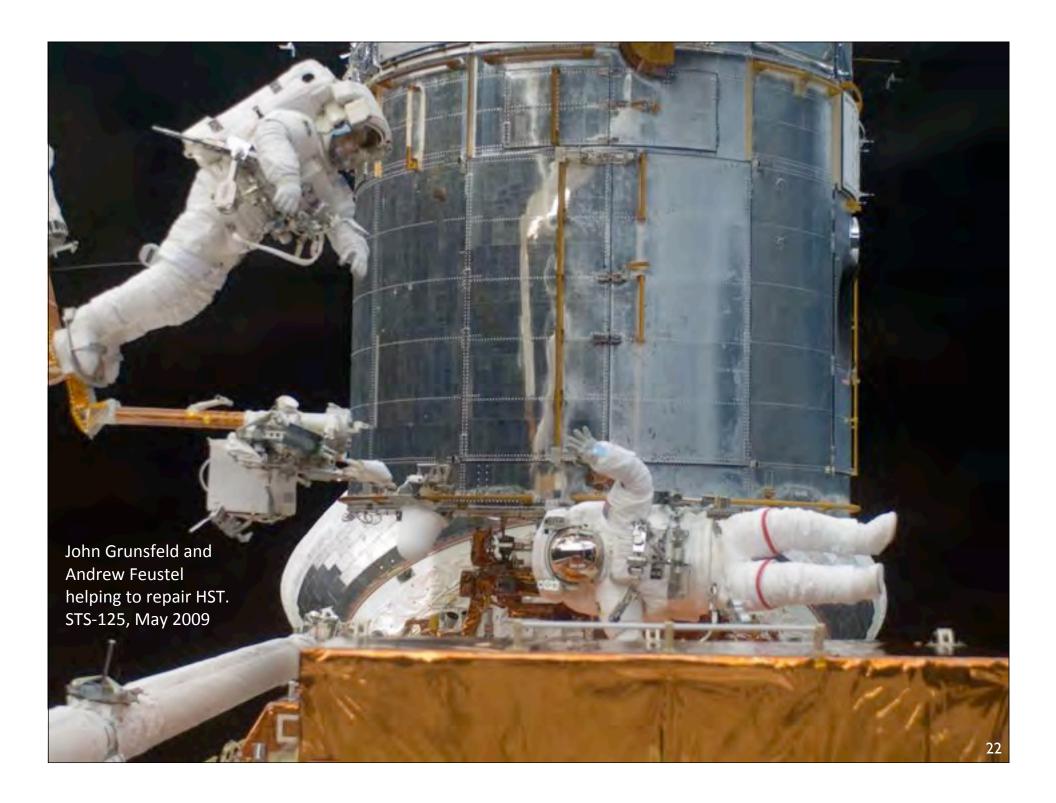


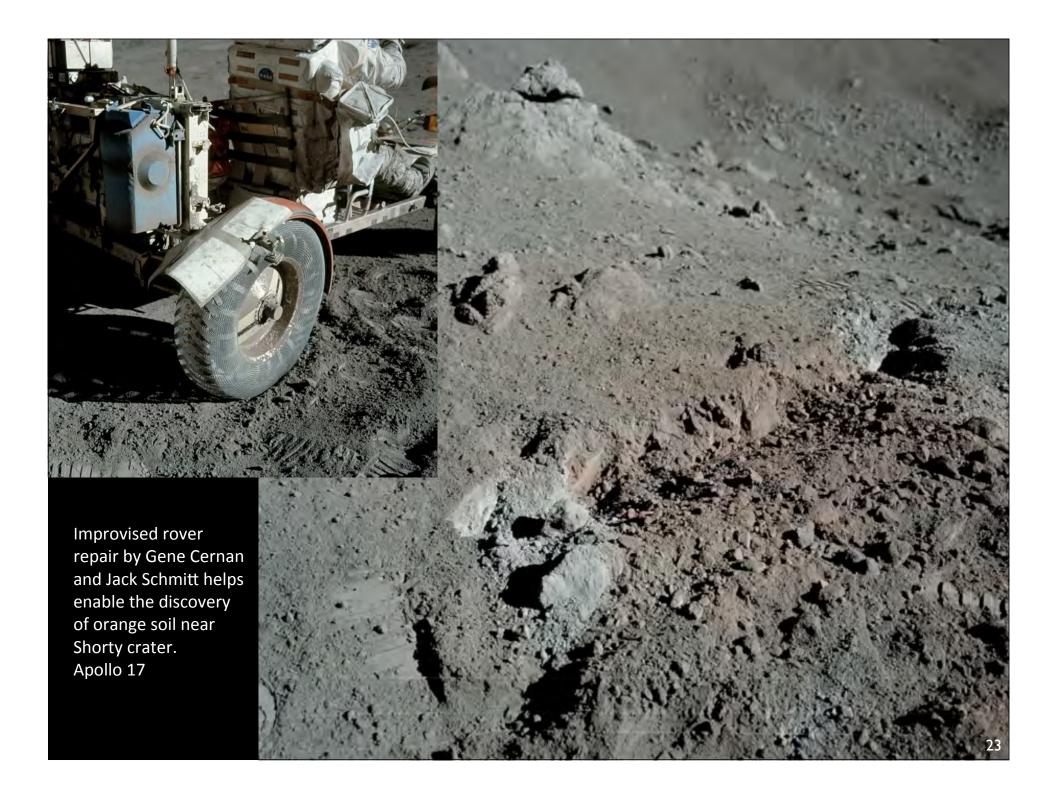














Contents lists available at ScienceDirect

#### Acta Astronautica





#### Crew on the ISS: Creativity or determinism?

Sergey K. Krikalev, Alexander Yu. Kalery, Igor V. Sorokin\*

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Flight control flexibility

#### ABSTRACT

Analyzing the experience of human flights to the *Mir* space station in 1986–2000 and to the ISS in 2000–2008, as well as *Space Shuttle* missions we can define structural and organizational tendencies in human missions to space and mission support. The tendency to the increased determinism in flight operations leads to lower flexibility of the "Crew-Mission Control Center" link in case of contingency. We justify the necessity to reduce the centralization of the control process and to hand over some mission control centers (MCC) authority to the International Space Station (ISS) crew. We conclude that human missions to the Moon and Mars where crew actions will be independent to a high degree will be impossible without resolution of this issue. Creativity and determinism should be properly balanced.

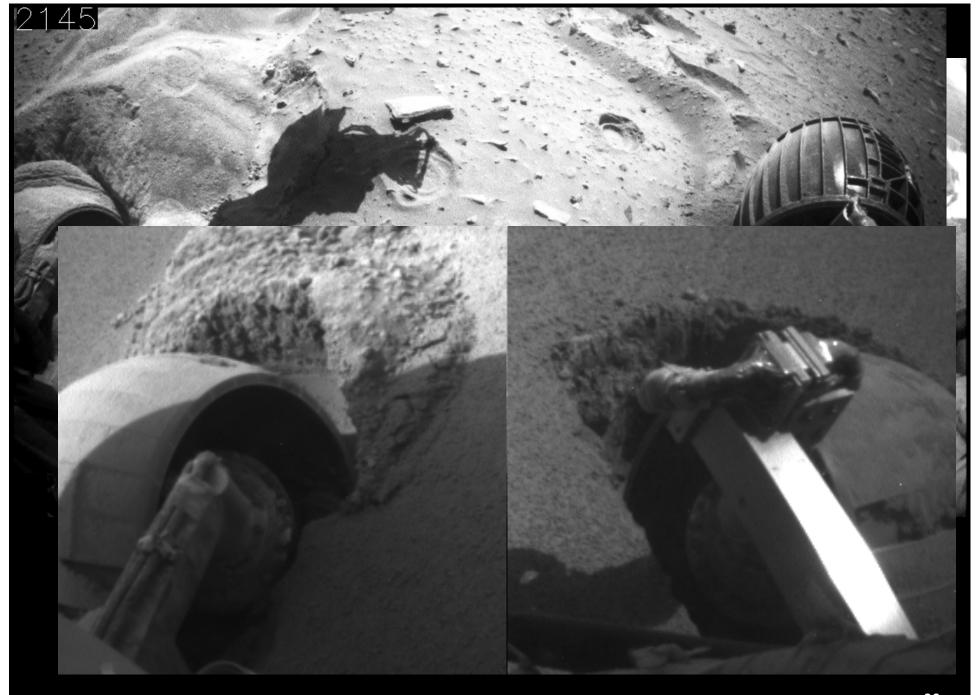
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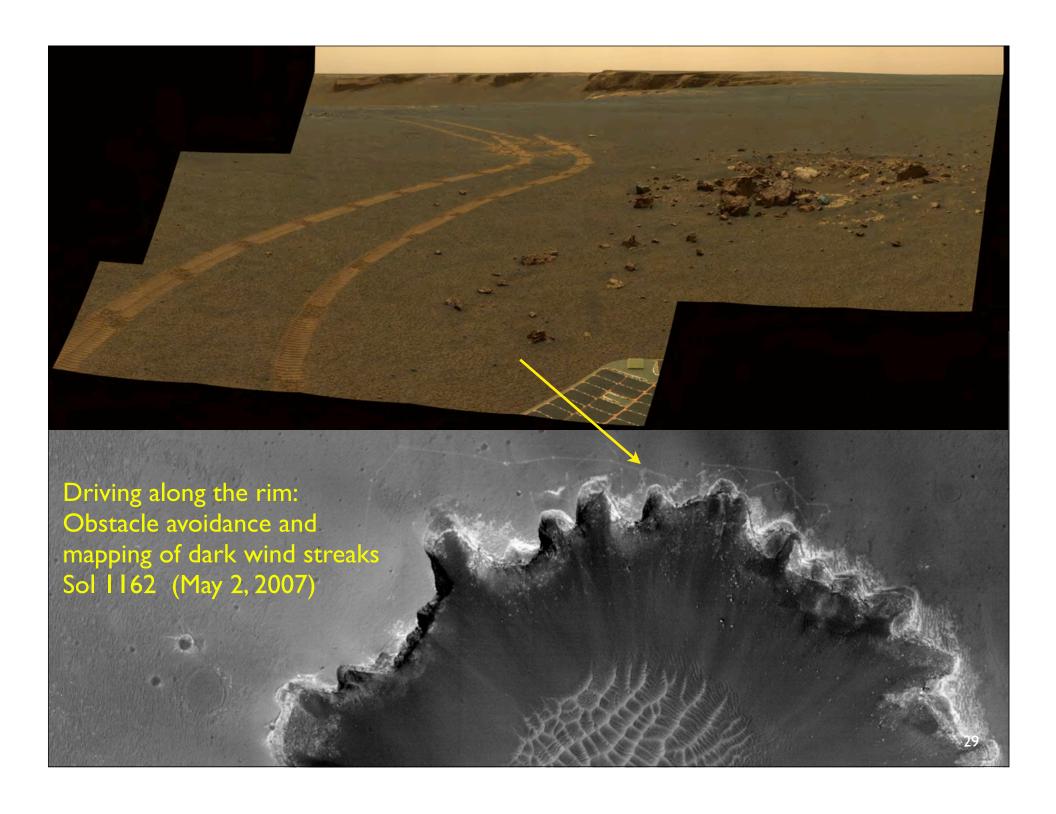


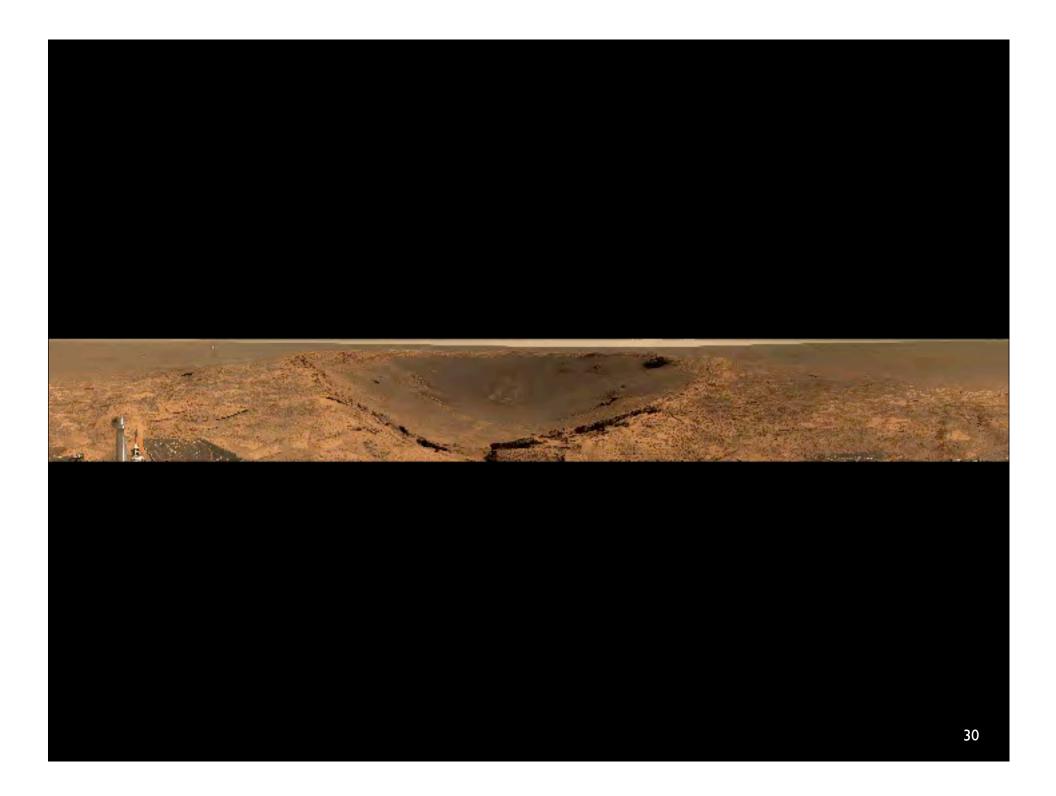


First 12 drill holes in Gale Crater (through sol 1261)...









### Important Drivers

- Is there added science and/or exploration value that telerobotic operations from Mars orbit provides, given the risks that the crew will be exposed to?
- If so, what specific attributes does low-latency provide that is worth that risk, versus just living with the current delay in communications?
- If not, are there technological advances or innovations that could provide that added value, helping to focus current/future development work?



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